



Optimization of Polytopic System Eigenvalues by Swarm of Particles

Jacek Kabziński, Jarosław Kacerka

Institute of Automatic Control
Lodz Univeristy of Technology, Poland



Plan

- Introduction
 - Eigenvalue optimization
 - Linear polytopic systems
- Problem formulation and features
- Proposed (U)PSO modifications
- Numerical experiments results
- Conclusions
- Discussion



Eigenvalue optimization

- fascinating and continuous challenge
- most popular problem: minimization of maximum real part of system eigenvalues
- applications: physic, chemistry, structural design, mechanics, etc.



Eigenvalue optimization

- **eigenvalues of dynamic systems:**
 - **measure of robustness**
 - **information regarding stability/instability**



Eigenvalue optimization

- **symmetric matrices:**
 - **may be solved e.g. by convex optimization**

Blanco, A.M., Bandoni, J.A.: Eigenvalue and Singular Value Optimization. In: ENIEF 2003 - XIII Congreso sobre Métodos Numéricos y sus Aplicaciones, pp. 1256–1272 (2003)

- **non-symmetric matrices:**
 - **non-convex**
 - **non-differentiable**
 - **multiple local optima**



Linear polytopic system

- system matrix:
- in a convex hull of vertices: A_1, \dots, A_N
- combination coefficients: $\alpha_1, \dots, \alpha_N$

$$\frac{dx}{dt} = A(\alpha)x \quad A(\alpha) = \sum_{i=1}^N \alpha_i A_i$$

$$\alpha = [\alpha_1, \alpha_2, \dots, \alpha_N]^T, \quad \alpha_i \geq 0, \quad i = 1, 2, \dots, N \quad \sum_{i=1}^N \alpha_i = 1$$

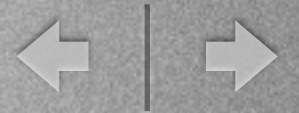


Problem formulation

$$\text{Minimize } f(\alpha) = \max_{1 \leq i \leq n} \text{Re} \lambda_i(A(\alpha))$$

$$\alpha = [\alpha_1, \alpha_2, \dots, \alpha_N]^T, \quad \alpha_i \geq 0, \quad i = 1, 2, \dots, N - 1$$

$$\sum_{i=1}^{N-1} \alpha_i \leq 1, \quad \alpha_N = 1 - \sum_{i=1}^{N-1} \alpha_i$$



Problem features

- N vertices
- $N-1$ optimization variables
- stable vertices $\not\Rightarrow$ stable polytopic system

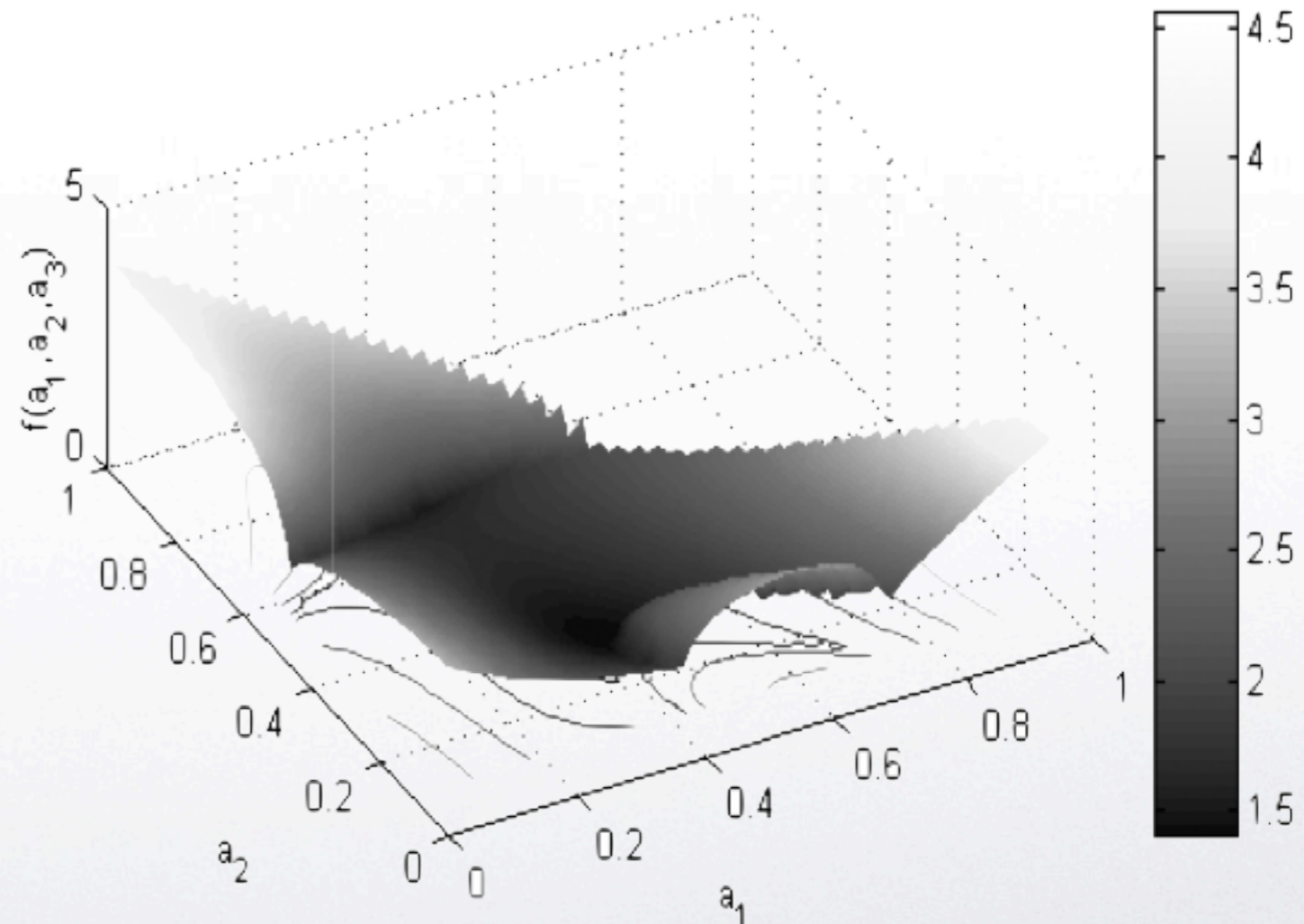
$$\begin{bmatrix} -0.1 & 2 \\ 0 & -0.2 \end{bmatrix} \begin{bmatrix} -2 & 1.9 \\ 1.9 & -2 \end{bmatrix} \quad \begin{bmatrix} -1.05 & 1.95 \\ 0.95 & -1.1 \end{bmatrix} \quad \begin{matrix} 0.2863 \\ -2.4363 \end{matrix}$$

- non-convex, non-differentiable, several local minima



Problem features

- hard constraints
- global minimum located on boundary or vertex





Particle Swarm Optimization

- stochastic optimization algorithm based on social simulation models
- multiple modifications, selected: UPSO
 - combines exploration and exploitation abilities
 - superiority in terms of success rate and number of function evaluations



Proposed modifications (I)

Constraints - initial position in N-1 dimensional simplex

- algorithm:

- random position in N-1 dimensional unit hypercube $\hat{\alpha} = [\alpha_1, \alpha_2, \dots, \alpha_{N-1}]^T$

- if $\sigma = \sum_{i=1}^{N-1} \alpha_i > 1$

divide $\hat{\alpha}$ by random coefficient bigger than σ :

$$\hat{\alpha} := \frac{\hat{\alpha}}{\sigma(1+r)}$$



Proposed modifications (2)

Constraints:

- hard - any point outside simplex is infeasible
- global minimum often on simplex face or vertex
- modification: ability to slide along face or edge



Proposed modifications

Algorithm:

- previous position: $\hat{\alpha} = [\alpha_1, \alpha_2, \dots, \alpha_{N-1}]^T$
- new position: $\hat{\beta} = [\beta_1, \beta_2, \dots, \beta_{N-1}]^T$

- calculate minimum distance t_{min} from $\hat{\beta}$ to boundaries:

$$\sum_{i=1}^{N-1} \alpha_i = 1 \quad \alpha_i = 0$$

- replace new position with intersection point:

$$\hat{\alpha}' = \hat{\beta} + t_{min} \cdot v$$

- neutralize velocity component orthogonal to boundary hyper-plane:

- for $\alpha_i = 0$ - appropriate component zeroed
- for $\sum_{i=1}^{N-1} \alpha_i = 1$ - velocity set to parallel component



Numerical experiments

- 150 random generated problems
- $n \in [2,6], N \in [3,5], A_{ij} \in [-5,5]$
- every problem sampled at 0.1 resolution + local optimizer: number of local minima, one “global” minimum
- 1 to 20 local minima (single minimum in 20% of problems)
- global minimum at space boundary - 50% of problems



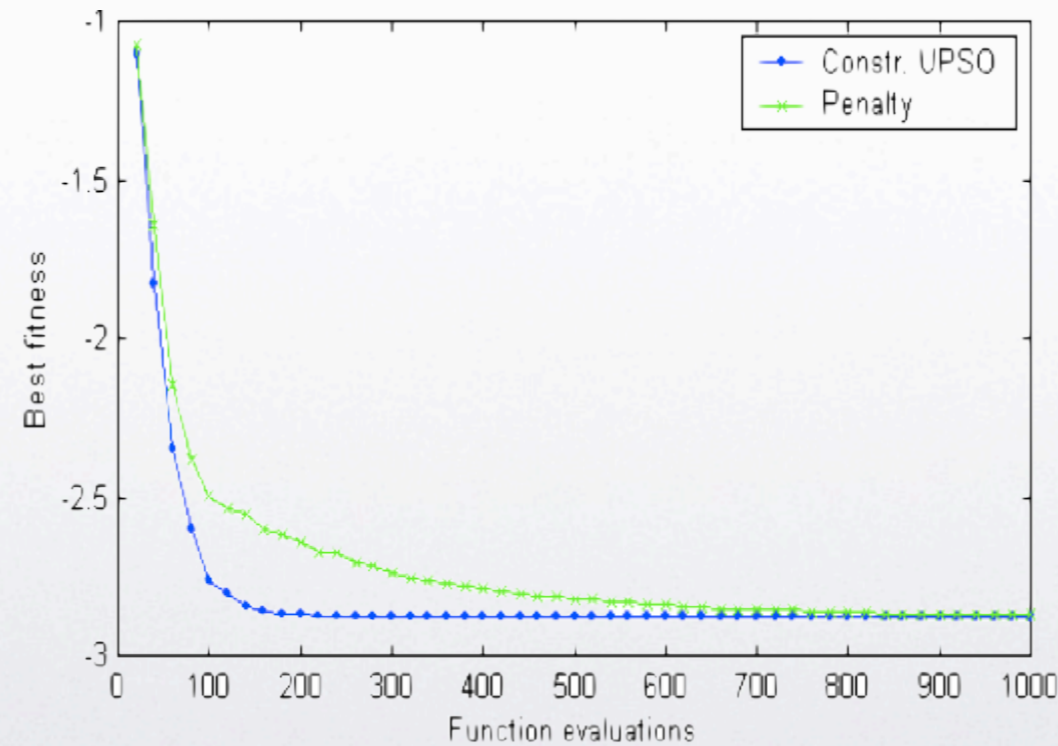
Numerical experiments

- For every problem 50 executions of:
 - proposed constrained UPSO (C-USPO)
 - UPSO constrained by penalty function
- Search successful if best fitness close to global minimum



Results

- success rate: 5% higher for C-UPSO
- convergence: C-UPSO up to 50% faster
- similar influence of number of minima on both algorithms





Results

- global minimum on the boundary:
- higher success rate of C-UPSO
- 60% less iterations of C-UPSO



Conclusions

- proposed two modifications of PSO:
- initialization constrained to $N-1$ dimensional simplex
- ability to slide along boundary
- increase in success rate and convergence
- applicable to other eigenvalue optimization problems